

A NUMERICAL METHOD FOR AN UNDERGROUND WASTE REPOSITORY PROBLEM WITH NON STANDART INTERFACE CONDITION



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A NUMERICAL METHOD
FOR AN UNDERGROUND
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PROBLEM WITH NON
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Setting The Physical Problem

Homogenization process

The non standart interface
condition Problem

Stationary problem

Equilibrium Formulation
The Approximate Problem
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NonStationary problem

Numerical Tests

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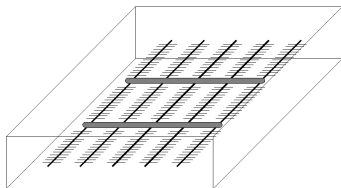
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- Convection diffusion problem
- A high number of small sources lying on hyperplane Σ ..
- Very small size details ($<$ one meter).
- Very large domain ($>$ few kilometers).
- Long time study ($>$ 10^6 years).
- \Rightarrow Direct numerical simulations for performance assesment not realistic.

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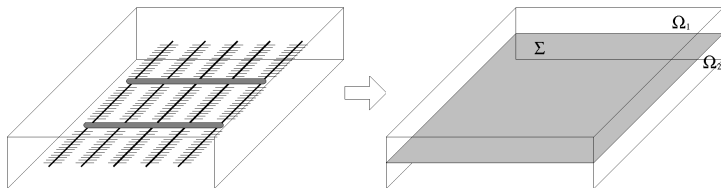
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- Separate the domain into two domains Ω_1 and Ω_2 ($\Sigma = \Omega_1 \cap \Omega_2$).
- Reduce the sources to only one on Σ .
- Coupling the problems in Ω_1 and Ω_2 by an interface condition on Σ , depending on physical parameters :
 - More simple case : Flux Jump on Σ .
 - More interesting case : differential problem on Σ .

The non standart interface condition Problem

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For sake of Simplicity, without transport :

$$\frac{\partial \phi}{\partial t} - \Delta \phi + \gamma \phi = f \quad \text{in } (\Omega_1 \cup \Omega_2), 0 < t \leq T \quad (1a)$$

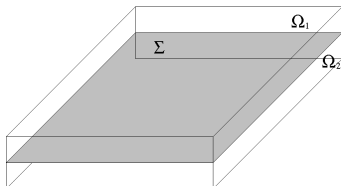
$$\phi = 0, \quad \text{on } (\Gamma \setminus \Sigma), 0 < t \leq T, \quad (1b)$$

$$\left[\frac{\partial \phi}{\partial n} \right]_{\Sigma} - \Delta_{\Sigma} \phi = g \quad \text{on } \Sigma, 0 < t \leq T, \quad (1c)$$

$$[\phi]_{\Sigma} = 0 \quad \text{on } \Sigma, 0 < t \leq T \quad (1d)$$

$$\phi(t=0, \cdot) = \phi_0 \quad \text{in } (\Omega_1 \cup \Omega_2) \quad (1e)$$

Where $[\cdot]$ denotes the jump through the interface Σ .



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Stationary problem

Let consider first the stationary case

(Coming from, for example, the implicit time discretization of the above problem)

$$-\Delta\phi + \phi = f \quad \text{in } (\Omega_1 \cup \Omega_2), \quad (2a)$$

$$\phi = 0, \quad \text{on } (\Gamma \setminus \Sigma), \quad (2b)$$

$$\left[\frac{\partial\phi}{\partial n} \right]_{\Sigma} - \Delta_{\Sigma}\phi = g \quad \text{on } \Sigma, \quad (2c)$$

$$[\phi]_{\Sigma} = 0 \quad \text{on } \Sigma \quad (2d)$$

Equilibrium Formulation

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Mixed Formulation for problems in $\Omega_i = 1, 2$.

$$p_i = \nabla \phi \quad \text{in } \Omega_i, i = 1, 2 \quad (3a)$$

$$-\operatorname{div} p_i + \phi = f \quad \text{in } \Omega_i, i = 1, 2 \quad (3b)$$

$$[p \cdot n] - \Delta_{\Sigma} \phi = g \quad \text{on } \Sigma \quad (3c)$$

$$\phi = 0, \quad \text{on } \Gamma \setminus \Sigma \quad (3d)$$

- Let us introduce the product space :

$$W = \prod_{i=1}^2 H(\operatorname{div}, \Omega_i) \text{ with } \|\cdot\|_W = \left(\sum_{i=1}^2 \|\cdot\|_{H(\operatorname{div}, \Omega_i)}^2 \right)^{1/2}$$

- We denote by λ_2 the trace of ϕ on Σ , $\lambda = \phi|_{\Sigma} \in H_0^1(\Sigma)$.

$$\forall q \in W, \sum_{i=1}^2 \langle p_i, q_i \rangle_{0, \Omega_i} + \langle \operatorname{div} p_i, \operatorname{div} q_i \rangle_{0, \Omega_i}$$

$$- \langle \lambda, [q, n] \rangle_{\Sigma} = - \sum_{i=1}^2 \langle f, \operatorname{div} q_i \rangle_{0, \Omega_i} \quad (4a)$$

$$\forall \psi \in H_0^1(\Sigma), \langle \nabla_{\Sigma} \phi, \nabla_{\Sigma} \psi \rangle_{0, \Sigma} + \langle [p \cdot n], \psi \rangle_{\Sigma} = \langle g, \psi \rangle_{0, \Sigma} \quad (4b)$$

Equilibrium Formulation

Find $(p, \lambda) \in W \times H_0^1(\Sigma)$ such that, $\forall (q, \psi) \in W \times H_0^1(\Sigma)$:

$$A((p, \lambda), (q, \psi)) = - \sum_{i=1}^2 \langle f, \operatorname{div} q_i \rangle_{0, \Omega_i} + \langle g, \psi \rangle_{\Sigma} \quad (5)$$

where the bilinear form $A(., .)$ is defined by

$$\begin{aligned} A((p, \lambda), (q, \psi)) &= \sum_{i=1}^2 \langle p_i, q_i \rangle_{0, \Omega_i} + \langle \operatorname{div} p_i, \operatorname{div} q_i \rangle_{0, \Omega_i} \\ &\quad - \langle \lambda, [q \cdot n] \rangle_{\Sigma} \\ &\quad + \langle \nabla_{\Sigma} \phi, \nabla_{\Sigma} \psi \rangle_{0, \Sigma} + \langle [p \cdot n], \psi \rangle_{\Sigma} . \quad (6) \end{aligned}$$

Theorem

There exists a unique solution (p, λ) of the weak formulation (5). Moreover ϕ is the weak solution of the problem (2).

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The Approximate Problem

Let us introduce finite dimensional subspaces

$$W_i^h \subset H(\text{div}, \Omega_i), \quad W_h = \prod_{i=1}^2 W_i^h, \quad \text{and} \quad M_H \subset H_0^1(\Sigma).$$

the abstract discrete formulation of (5) is given by :

Find $(p_h, \lambda_H) \in W_h \times M_H$ such that, $\forall (q_h, \psi_H) \in W_h \times M_H$,

$$A((p_h, \lambda_H), (q_h, \psi_H)) = - \sum_{i=1}^2 \langle f, \text{div } q_h \rangle_{0, \Omega_i} + \langle g, \psi_H \rangle_{\Sigma} \quad (7)$$

The Approximate Problem

Using Lax-Milgram theorem and Céa Lemma leads to the following approximation result

Theorem

Let $(p, \lambda) \in W \times H_0^1(\Sigma)$ be the solution of the continuous problem (5). The problem (7) admits a unique solution $(p_h, \lambda_H) \in W_h \times M_H$ and there exists a constant C independent of h and H such that

$$\|p - p_h\|_W + \|\lambda - \lambda_H\|_{1,\Sigma} \leq C \inf_{(q_h, \psi_H) \in W_h \times M_H} \left\{ \|p - q_h\|_W + \|\lambda - \psi_H\|_{1,\Sigma} \right\} \quad (8)$$

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Finite Element Discretization

Basic finite element Choice of W_i^h and M_H :

- regular triangulations \mathcal{T}_h of the domain Ω with triangular ($d = 2$) and tetrahedral ($d = 3$) finite elements whose diameters are less or equal than h , and

$$W_i^h = \{q_h \in H(\text{div}, \Omega_i); \forall T \in \mathcal{T}_h, q_{h|T} \in RT_k(T)\}$$

where $RT_k(T)$ is the Raviart-Thomas finite element space

- a regular subdivision \mathcal{S}_H of Σ with intervals ($d = 2$) or triangles ($d = 3$) with diameters less or equal than H , and

$$M_H = \{\psi_H \in H_0^1(\Sigma); \forall S \in \mathcal{S}_H, \psi_{H|S} \in P_l(S)\}$$

l being a given positive integer.

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Finite Element Discretization

For such a choice of discretizations, one can state the following error estimate,

Theorem

Assuming the solution (p, λ) of (5) is such that $p \in \prod_{i=1}^2 (H^\sigma(\Omega_i))^d$, and $\operatorname{div} p \in \prod_{i=1}^2 (H^\sigma(\Omega_i))^d$, $0 < \sigma \leq k + 1$, and $\lambda \in H^s(\Sigma)$ with $1 < s < l + 1$, there exists a positive constant C independent of discretization parameters such that

$$\|p - p_h\|_W + \|\lambda - \lambda_H\|_{1,\Sigma} \leq C \{ \mathcal{O}(h^\sigma) + \mathcal{O}(H^{s-1}) \}$$

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Let us introduce a discrete equilibrium formulation of the implicit non stationary problem :

$$(7) \left\{ \begin{array}{l} \left(\frac{\phi_h^{k+1} - \phi_h^k}{\Delta t}, \mu_h \right) - (\operatorname{div} p_h^{k+1}, \mu_h) = (f, \mu_h) \\ (p_h^{k+1}, q_h) + (\operatorname{div} q_h, \phi_h^{k+1}) = \langle [q_h \cdot n], \lambda_h^{k+1} \rangle \\ \langle \nabla_{\Sigma} \lambda_h^{k+1}, \nabla_{\Sigma} \alpha_h \rangle = - \langle [p_h^{k+1} \cdot n], \alpha_h \rangle + \langle g, \alpha_h \rangle \end{array} \right.$$

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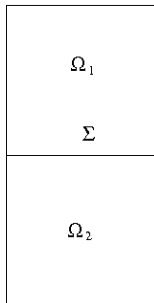
This scheme (7) is proved to be stable. Moreover if

*$p \in L^{\infty}(\prod_{i=1}^2 (H^{\sigma_2}(\Omega_i))^d)$, $1/2 < \sigma_2 \leq 1$,
 $\phi \in H^{1+\sigma}(L^2(\Omega))$, $\lambda \in L^{\infty}(H^{1+\sigma_1}(\Sigma))$, with, $0 < \sigma, \sigma_1 \leq 1$,
the solution satisfies the following error estimate,*

$$\left(\sup_{1 \leq k \leq N} \|\phi^k - \phi_h^k\|_{0,\Omega} \right) + \Delta t \|p^k - p_h^k\|_{0,\Omega} + \Delta t |\lambda^k - \lambda_h^k|_{1,\Sigma} \leq$$

$$C \left(|\phi|_{H^{1+\sigma}(L^2(\Omega))} + |p|_{L^{\infty}(\prod_{i=1}^2 (H^{\sigma}(\Omega_i))^d)} + |\lambda|_{L^{\infty}(H^{1+\sigma_1}(\Sigma))} \right) [H^{\sigma_1} + h^{\sigma_2} + |\Delta t|^{\sigma+1/2}]$$

- 2 dimensional geometry



- Stationary Case.



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Domain Decomposition Algorithm

Let consider $(p_{h,i})$, $i = 1, 2$ the restriction of (p_h) to the domain Ω_i . let denote

$$a_i(p_{h,i}, q_{h,i}) = \langle p_{h,i}, q_{h,i} \rangle_{0, \Omega_i} + \langle \operatorname{div} p_{h,i}, \operatorname{div} q_{h,i} \rangle_{0, \Omega_i} \quad i = 1, 2$$

$$b_i(\lambda_h, q_{h,i}) = \langle \lambda_h, [q_{h,i} \cdot n] \rangle_{\Sigma} - \langle f_{h,i}, \operatorname{div} q_{h,i} \rangle_{0, \Omega_i} \quad i = 1, 2$$

$$a_{\Sigma}(\phi_H, \psi_H) = \langle \nabla_{\Sigma} \phi_H, \nabla_{\Sigma} \psi_H \rangle_{\Sigma} \quad (11)$$

$$b_{\Sigma}(p_h, \psi_H) = \langle g_H - [p_h \cdot n], \psi_H \rangle_{\Sigma} \quad (12)$$

Domain décomposition :

1 solving in // two uncoupled problems in Ω_1 and Ω_2 ,

2 Solving the coupling problem on Σ

Let denote $(p_{h,i}^n, \lambda_h^n, \phi_H^n)$ the n -th decomposition domain iteration values of $(p_{h,i}, \lambda_h, \phi_H)$

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Decomposition Domain Algorithm

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Algorithm 1 Domain decomposition algorithm

λ^0 given, $n = 1$;

$\varepsilon \ll 1$ given, $error = 1$;

while $error \geq \varepsilon$ **do**

Solve $a_i(p_{h,i}^n, q_{h,i}) = b_i(\lambda^{n-1}, q_{h,i})$, $i = 1, 2$

Solve $a_\Sigma(\phi^n, \psi) = b_\Sigma(p_{h,i}^n, \psi)$,

$\lambda^n := \phi|_\Sigma^n$;

$n := n + 1$

$$error = \left(\sum_{i=1,2} \|p_{h,i}^n - p_{h,i}^{n-1}\|_{0,\Omega_i}^2 \right)^{1/2}$$

end while

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Let consider the analytic test case :

$$\phi(x, y) = \begin{cases} x(1-x)(2-y) & \text{if } (x, y) \in \Omega_1 \\ x(1-x) & \text{if } (x, y) \in \Sigma \\ x(1-x)\sin(\pi/2y) & \text{if } (x, y) \in \Omega_2 \end{cases}$$

which is solution of the initial problem with source term (f, g) defined by

$$f(x, y) = \begin{cases} (2 + x(1-x))(2-y) & \text{if } (x, y) \in \Omega_1 \\ (x(1-x)(1 + \pi^2/4) + 2)\sin(\pi/2y) & \text{if } (x, y) \in \Omega_2 \end{cases}$$
$$g(x) = 2 - x(1-x)$$



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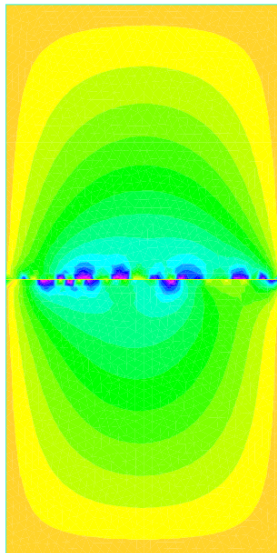
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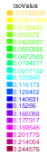
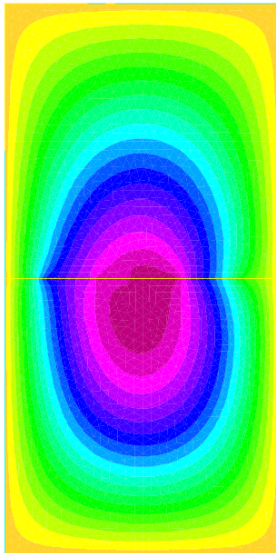
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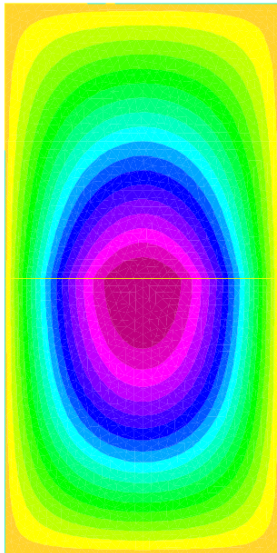
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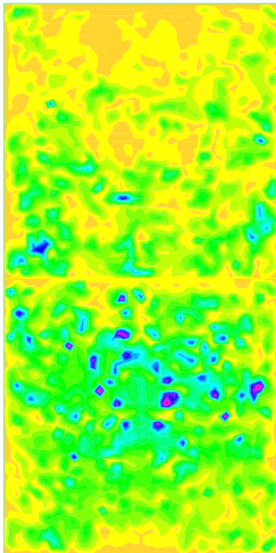
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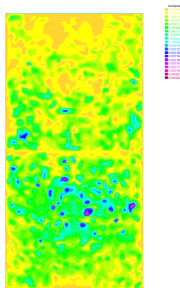
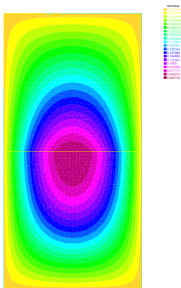
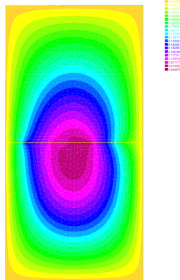
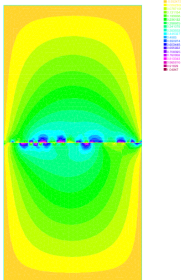
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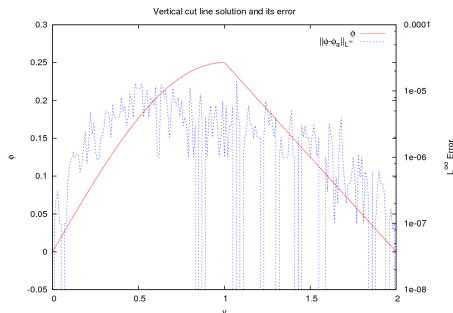
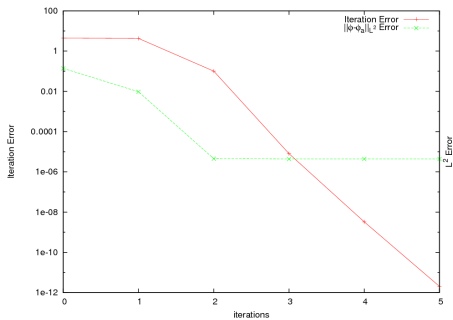
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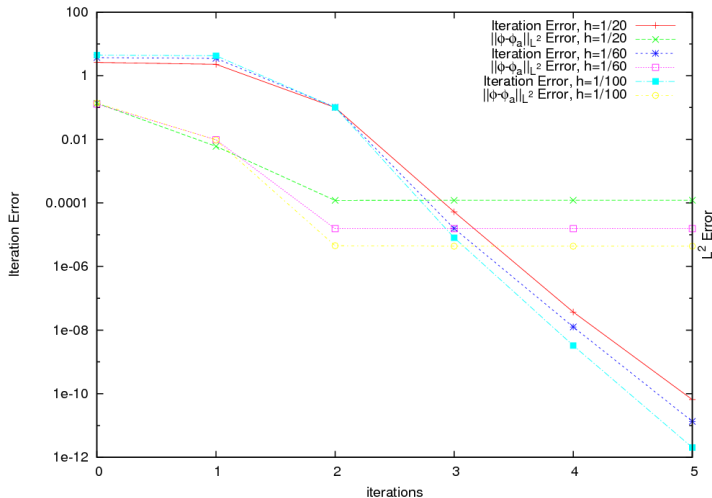
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Conclusions

- Conservative method for non standart interface condition
- Coupled system in which all matching conditions remain implicit.
- Numerical scheme and errors estimates.
- Decomposition domain algorithm.
- → to be implemented in the underground waste repository situation.

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