# Retraction Method in the Qualitative Analysis of the Solutions of the Quasilinear Second Order Differential Equation 

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Abstract. The quasilinear second order differential equation

$$
y^{\prime \prime}+P(y, t) y^{\prime}+Q(y, t) y=F(y, t)
$$

where $P, Q, F \in C(\mathbb{R} \times I), I=(a, \infty), a \in \mathbb{R}$, is under consideration. This paper deals with the behaviour, approximation and stability of solutions of this equation. Behaviour of integral curves in neighbourhoods of an arbitrary integral curve is considered. The qualitative analysis theory and topological retraction method are used. The general results and a several appropriate examples are considered and discussed.

AMS subject classification: 34 C 05
Key words: quasilinear differential equation, behaviour of solutions

## 1. Introduction

Let us consider the quasilinear second order differential equation

$$
\begin{equation*}
y^{\prime \prime}+P(y, t) y^{\prime}+Q(y, t) y=F(y, t) \tag{1}
\end{equation*}
$$

where $P, Q, F \in C(\mathbb{R} \times I), I=(a, \infty), a \in \mathbb{R}$. Let

$$
\Gamma=\{(y, t) \in \mathbb{R} \times I \mid y=\psi(t), t \in I\}
$$

where $\psi(t) \in C^{2}(I)$ is an arbitrary integral curve.
In this paper the behaviour of the solutions of equation (1) in the neighbourhood of curve $\Gamma$ is considered. The notations $\psi_{0}=\psi\left(t_{0}\right), y_{0}=y\left(t_{0}\right), y_{0}^{\prime}=y^{\prime}\left(t_{0}\right), t_{0} \in I$ are going to be used.

Let $r_{1}, r_{2} \in C^{1}(I), r_{1}(t)>0, r_{2}(t)>0$ on $I$. Let us consider the solutions $y(t)$ of equation (1) which satisfy on $I$, either the conditions

$$
\begin{equation*}
\left|y_{0}-\psi_{0}\right| \leq r_{2}\left(t_{0}\right), \quad\left|y_{0}^{\prime}-\psi_{0}^{\prime}\right| \leq r_{1}\left(t_{0}\right), \tag{2}
\end{equation*}
$$

or

$$
\begin{equation*}
\frac{\left(y_{0}-\psi_{0}\right)^{2}}{r_{2}^{2}\left(t_{0}\right)}+\frac{\left(y_{0}^{\prime}-\psi_{0}^{\prime}\right)^{2}}{r_{1}^{2}\left(t_{0}\right)} \leq 1 \tag{3}
\end{equation*}
$$

[^0]
## 2. Preliminaries

Let

$$
\begin{equation*}
y^{\prime}=x \tag{4}
\end{equation*}
$$

where $x=x(t)$ is a new unknown function. Equation (1) is transformed into a quasilinear system of equations

$$
\left\{\begin{array}{l}
x^{\prime}=-P(y, t) x-Q(y, t) y+F(y, t)  \tag{5}\\
y^{\prime}=x \\
t^{\prime}=1
\end{array}\right.
$$

Let $(\varphi(t), \psi(t), t), t \in I$, where $\varphi(t)=\psi^{\prime}(t)$, be an arbitrary integral curve of the system (5), and let $\Omega=\mathbb{R}^{2} \times I$.

We shall consider the behaviour of the integral curve $(x(t), y(t), t)$ of (5) with respect to the sets

$$
\sigma=\left\{(x, y, t) \in \Omega| | x-\varphi(t)\left|<r_{1}(t),|y-\psi(t)|<r_{2}(t)\right\}\right.
$$

and

$$
\omega=\left\{(x, y, t) \in \Omega \left\lvert\, \frac{(x-\varphi(t))^{2}}{r_{1}^{2}(t)}+\frac{(y-\psi(t))^{2}}{r_{2}^{2}(t)} \leq 1\right.\right\}
$$

The boundary surfaces of $\sigma$ and $\omega$ are, respectively,

$$
\begin{aligned}
X_{i} & =\left\{(x, y, t) \in \mathrm{Cl} \sigma \mid H_{i}^{1}(x, y, t) \equiv(-1)^{i}(x-\varphi(t))-r_{1}(t)=0\right\}, \\
Y_{i} & =\left\{(x, y, t) \in \mathrm{Cl} \sigma \mid H_{i}^{2}(x, y, t) \equiv(-1)^{i}(y-\psi(t))-r_{2}(t)=0\right\}, \\
W & =\left\{(x, y, t) \in \mathrm{Cl} \omega \left\lvert\, H(x, y, t) \equiv \frac{(x-\varphi(t))^{2}}{r_{1}^{2}(t)}+\frac{(y-\psi(t))^{2}}{r_{2}^{2}(t)}-1=0\right.\right\} .
\end{aligned}
$$

To prove our results we need the following results concerning the applicability of the qualitative analysis theory and topological retraction method of T. Waževski [6].

Let us denote the tangent vector field to an integral curve $(x(t), y(t), t)$ of (5) by $T$. The vectors $\nabla H_{i}^{1}, \nabla H_{i}^{2}$ and $\nabla H$ are the outer normals on surfaces $X_{i}, Y_{i}$ and $W$, respectively. We have

$$
\begin{aligned}
T(x, y, t)= & (-P(y, t) x-Q(y, t) y+F(y, t), x, 1) \\
\nabla H_{i}^{1}(t)= & \left((-1)^{i}, 0,(-1)^{i-1} \varphi^{\prime}-r_{1}^{\prime}\right), \quad i=1,2 \\
\nabla H_{i}^{2}(t)= & \left(0,(-1)^{i},(-1)^{i-1} \psi^{\prime}-r_{2}^{\prime}\right), \quad i=1,2, \\
\frac{1}{2} \nabla H(x, y, t)= & \left(\frac{x-\varphi}{r_{1}^{2}}, \frac{y-\psi}{r_{2}^{2}},\right. \\
& \left.-\frac{(x-\varphi)^{2} r_{1}^{\prime}}{r_{1}^{3}}-\frac{(y-\psi)^{2} r_{2}^{\prime}}{r_{2}^{3}}-\frac{(x-\varphi) \varphi^{\prime}}{r_{1}^{2}}-\frac{(y-\psi) \psi^{\prime}}{r_{2}^{2}}\right) .
\end{aligned}
$$

By means of scalar products $\pi_{i}^{1}(x, y, t)=\left(\nabla H_{i}^{1}, T\right)$ on $X_{i}, \pi_{i}^{2}(x, y, t)=\left(\nabla H_{i}^{2}, T\right)$ on $Y_{i}$, and $\pi(x, y, t)=\left(\frac{1}{2} \nabla H, T\right)$ on $W$, we shall establish the existence and behaviour of integral curves of (5) with respect to the sets $\sigma$ and $\omega$, respectively.

Let us denote by $S^{p}(I), p \in\{0,1,2\}$, a class of solutions $(x(t), y(t), t)$ of the system (5) defined on $I$, which depends on $p$ parameters. We shall simply say that the class of solutions $S^{p}(I)$ belongs to the set $\eta(\eta=\omega$ or $\eta=\sigma)$ if graphs of functions in $S^{p}(I)$ are contained in $\eta$. In that case we shall write $S^{p}(I) \subset \eta$. For $p=0$ we have the notation $S^{0}(I)$, which means that there exists at least one solution $(x(t), y(t), t)$ on $I$ of the system (5), whose graph belongs to the set $\eta$.

The results of this paper are based on the following Lemmas (see $[4,5]$ ).
Lemma 1. If, for the system (5), the scalar product $\pi<0$ on $W$ ( $\pi_{i}^{k}<0$ on $\partial \sigma=$ $X_{1} \cup X_{2} \cup Y_{1} \cup Y_{2}, i=1,2, k=1,2$ ), then the system (5) has a class of solutions $S^{2}(I)$ belonging to the set $\omega$ for all $t \in I$, i.e., $S^{2}(I) \subset \omega\left(S^{2}(I) \subset \sigma\right)$.

Lemma 2. If, for the system (5), the scalar product $\pi>0$ on $W$ ( $\pi_{i}^{k}>0$ on $\partial \sigma=$ $X_{1} \cup X_{2} \cup Y_{1} \cup Y_{2}, i=1,2, k=1,2$ ), then the system (5) has at least one solution on $I$ whose graph belongs to the set $\omega$ for all $t \in I$, i.e., $S^{0}(I) \subset \omega\left(S^{0}(I) \subset \sigma\right)$.

Lemma 3. If, for the system (5), the scalar product $\pi_{i}^{1}<0$ on $X_{1} \cup X_{2}$, and $\pi_{i}^{2}>0$ on $Y_{1} \cup Y_{2}$ (or reversely), then the system (5) has a class of solutions $S^{1}(I)$ belonging to the set $\sigma$ for all $t \in I$, i.e., $S^{1}(I) \subset \sigma$.

## 3. Main results

Theorem 1. Let $P(y, t), Q(y, t), F(y, t) \in C(\mathbb{R} \times I)$ satisfy the conditions:

$$
\begin{array}{ll}
\left|P\left(y_{1}, t\right)-P\left(y_{2}, t\right)\right|<L_{1}\left|y_{1}-y_{2}\right|, & \left(y_{1}, t\right),\left(y_{2}, t\right) \in \mathbb{R} \times I, \\
\left|Q\left(y_{1}, t\right)-Q\left(y_{2}, t\right)\right|<L_{2}\left|y_{1}-y_{2}\right|, & \left(y_{1}, t\right),\left(y_{2}, t\right) \in \mathbb{R} \times I, \\
\left|F\left(y_{1}, t\right)-F\left(y_{2}, t\right)\right|<L_{3}\left|y_{1}-y_{2}\right|, & \left(y_{1}, t\right),\left(y_{2}, t\right) \in \mathbb{R} \times I, \tag{8}
\end{array}
$$

and let $r_{1}, r_{2} \in C^{1}(I), r_{1}(t)>0, r_{2}(t)>0$. Then:
(i) If the conditions

$$
\begin{gather*}
\left(L_{1}|\varphi|+L_{2}|\psi|+L_{3}+|Q(y, t)|\right) r_{2}<r_{1}^{\prime}+P(y, t) r_{1},  \tag{9}\\
r_{1}<r_{2}^{\prime}, \tag{10}
\end{gather*}
$$

are satisfied on $\mathrm{Cl} \sigma$, then all solutions $y(t)$ of the problem (1), (2) satisfy the conditions

$$
\begin{equation*}
|y(t)-\psi(t)|<r_{2}(t), \quad\left|y^{\prime}(t)-\psi^{\prime}(t)\right|<r_{1}(t), \quad \text { for } \quad t>t_{0} . \tag{11}
\end{equation*}
$$

(ii) If the conditions

$$
\begin{gather*}
\left(L_{1}|\varphi|+L_{2}|\psi|+L_{3}+|Q(y, t)|\right) r_{2}<-r_{1}^{\prime}-P(y, t) r_{1}  \tag{12}\\
r_{1}<-r_{2}^{\prime} \tag{13}
\end{gather*}
$$

are satisfied on $\mathrm{Cl} \sigma$, then at least one solution of the problem (1), (2) satisfies the conditions (11).
(iii) If the conditions (9) and (13), or (10) and (12) are satisfied on $\mathrm{Cl} \sigma$, then the problem (1), (2) has one-parameter class of solutions satisfying the conditions (11).

Proof. We shall consider the equation (1) through the equivalent system (5). Let us consider the integral curves of the system (5) with respect to the set $\sigma$. For the scalar products $\pi_{i}^{1}(x, y, t)$ on $X_{i}$ and $\pi_{i}^{2}(x, y, t)$ on $Y_{i}$, we have:

$$
\begin{aligned}
& \pi_{i}^{1}(x, y, t)=(-1)^{i}[-P(y, t) x-Q(y, t) y+F(y, t)]+(-1)^{i-1} \varphi^{\prime}-r_{1}^{\prime} \\
&=(-1)^{i}[-P(y, t)(x-\varphi)-Q(y, t)(y-\psi)+F(y, t) \\
&\left.-P(y, t) \varphi-Q(y, t) \psi-\varphi^{\prime}\right]-r_{1}^{\prime} \\
&=-P(y, t) r_{1}+(-1)^{i}[-Q(y, t)(y-\psi)+F(y, t) \\
&\left.-P(y, t) \varphi-Q(y, t) \psi-\varphi^{\prime}\right]-r_{1}^{\prime}, \\
& \pi_{i}^{2}(x, y, t)=(-1)^{i} x+(-1)^{i-1} \psi^{\prime}-r_{2}^{\prime}=(-1)^{i}(x-\varphi)-r_{2}^{\prime} .
\end{aligned}
$$

(i) According to the conditions (6)-(8), (9) and (10), the following estimates for $\pi_{i}^{1}$ on $X_{i}$ and $\pi_{i}^{2}$ on $Y_{i}$ are valid, respectively:

$$
\begin{aligned}
\pi_{i}^{1}(x, y, t) \leq & -P(y, t) r_{1}+|Q(y, t)| r_{2} \\
& \quad+\left|F(y, t)-P(y, t) \varphi-Q(y, t) \psi-\varphi^{\prime}\right|-r_{1}^{\prime} \\
\leq & -P(y, t) r_{1}+|Q(y, t)| r_{2}+|F(y, t)-F(\psi, t)| \\
& \quad+|P(\psi, t)-P(y, t)||\varphi|+|Q(\psi, t)-Q(y, t)||\psi|-r_{1}^{\prime} \\
\leq & -P(y, t) r_{1}+|Q(y, t)| r_{2}+\left(L_{3}+L_{1}|\varphi|+L_{2}|\psi|\right) r_{2}-r_{1}^{\prime}<0 \\
\pi_{i}^{2}(x, y, t) \leq & r_{1}-r_{2}^{\prime}<0
\end{aligned}
$$

Accordingly, set $\partial \sigma=X_{1} \cup X_{2} \cup Y_{1} \cup Y_{2}$ is a set of points of strict entrance of integral curves of the system (5) with respect to the sets $\sigma$ and $\Omega$. Hence, all solutions of the system (5) which satisfy the conditions

$$
\left|x_{0}-\varphi_{0}\right| \leq r_{1}\left(t_{0}\right), \quad\left|y_{0}-\psi_{0}\right| \leq r_{2}\left(t_{0}\right), \quad\left(x_{0}=x\left(t_{0}\right)\right),
$$

also satisfy conditions

$$
|x(t)-\varphi(t)|<r_{1}(t), \quad|y(t)-\psi(t)|<r_{2}(t), \quad \text { for } \quad t>t_{0} .
$$

Since, in view of (4),

$$
x_{0}-\varphi_{0}=y_{0}^{\prime}-\psi_{0}^{\prime}
$$

all solutions of the problem (1), (2) satisfy the conditions (11).
(ii) According to the conditions (6)-(8), (12) and (13), the following estimates for $\pi_{i}^{1}$ on $X_{i}$ and $\pi_{i}^{2}$ on $Y_{i}$ are valid, respectively:

$$
\begin{aligned}
& \pi_{i}^{1}(x, y, t) \geq-P(y, t) r_{1}+|Q(y, t)|\left(-r_{2}\right) \\
& \quad-\left|F(y, t)-P(y, t) \varphi-Q(y, t) \psi-\varphi^{\prime}\right|-r_{1}^{\prime} \\
& \geq-P(y, t) r_{1}-|Q(y, t)| r_{2}-|F(y, t)-F(\psi, t)| \\
& \quad-|P(\psi, t)-P(y, t)||\varphi|-|Q(\psi, t)-Q(y, t)||\psi|-r_{1}^{\prime} \\
& \geq-P(y, t) r_{1}-|Q(y, t)| r_{2}-\left(L_{3}+L_{1}|\varphi|+L_{2}|\psi|\right) r_{2}-r_{1}^{\prime}>0, \\
& \pi_{i}^{2}(x, y, t) \geq-r_{1}-r_{2}^{\prime}>0 .
\end{aligned}
$$

Accordingly, set $\partial \sigma$ is a set of points of strict exit of integral curves of the system (5) with respect to sets $\sigma$ and $\Omega$. Hence, according to T .Wažewski's retraction method [6], the system (5) has at least one solution belonging to the set $\sigma$ for all $t \in I$. Consequently, the problem (1), (2) has at least one solution satisfying the conditions (11).
(iii) In this case $X_{1} \cup X_{2}$ is a set of points of strict exit, and $Y_{1} \cup Y_{2}$ is a set of points of strict entrance (or reversely) of integral curves of the system (5) with respect to the sets $\sigma$ and $\Omega$. According to the retraction method, the system (5) has one-parameter class of solutions belonging to the set $\sigma$ for all $t \in I$. Hence, the problem (1), (2) also has one-parameter class of solutions satisfying the conditions (11).

Let us consider now the solutions $y(t)$ of equation (1) which satisfy the condition (3).

Theorem 2. Let $P(y, t), Q(y, t), F(y, t) \in C(\mathbb{R} \times I)$, and let the conditions (6), (7) and (8) be satisfied. Let $r_{1}, r_{2} \in C^{1}(I), r_{1}(t)>0, r_{2}(t)>0$, and

$$
\begin{equation*}
\left(\left(L_{1}|\varphi|+L_{2}|\psi|+L_{3}\right) r_{2}^{2}+\left|r_{1}^{2}-Q(y, t) r_{2}^{2}\right|\right)^{2}<4 r_{1} r_{2}\left(P(y, t) r_{1}+r_{1}^{\prime}\right) r_{2}^{\prime} \tag{14}
\end{equation*}
$$

Then:
(i) If

$$
\begin{equation*}
r_{2}^{\prime}>0 \tag{15}
\end{equation*}
$$

then all solutions $y(t)$ of the problem (1), (3) satisfy the condition

$$
\begin{equation*}
\frac{(y(t)-\psi(t))^{2}}{r_{2}^{2}(t)}+\frac{\left(y^{\prime}(t)-\psi^{\prime}(t)\right)^{2}}{r_{1}^{2}(t)}<1, \quad \text { for } \quad t>t_{0} \tag{16}
\end{equation*}
$$

(ii) If

$$
\begin{equation*}
r_{2}^{\prime}<0 \tag{17}
\end{equation*}
$$

then at least one solution of the problem (1), (3) satisfies the condition (16).

Proof. We shall consider the equation (1) through the equivalent system (5). Let us consider the integral curves of the system (5) with respect to the set $\omega$. For the scalar product $\pi(x, y, t)=\left(\frac{1}{2} \nabla H, T\right)$ on the surface $W$, we have:

$$
\begin{aligned}
& \pi(x, y, t)=[-P(y, t) x-Q(y, t) y+F(y, t)] \frac{x-\varphi}{r_{1}^{2}}+x \frac{y-\psi}{r_{2}^{2}} \\
&-\frac{(x-\varphi)^{2} r_{1}^{\prime}}{r_{1}^{3}}-\frac{(y-\psi)^{2} r_{2}^{\prime}}{r_{2}^{3}}-\frac{(x-\varphi) \varphi^{\prime}}{r_{1}^{2}}-\frac{(y-\psi) \psi^{\prime}}{r_{2}^{2}} .
\end{aligned}
$$

If we introduce the notation

$$
X=\frac{x-\varphi}{r_{1}}, \quad Y=\frac{y-\psi}{r_{2}}
$$

we have:

$$
\begin{aligned}
\pi(x, y, t)= & {\left[-P(y, t)-\frac{r_{1}^{\prime}}{r_{1}}\right] X^{2}+\left[-Q(y, t) \frac{r_{2}}{r_{1}}+\frac{r_{1}}{r_{2}}\right] X Y-\frac{r_{2}^{\prime}}{r_{2}} Y^{2} } \\
& \quad+\left[-P(y, t) \varphi-Q(y, t) \psi+F(y, t)-\varphi^{\prime}\right] \frac{X}{r_{1}} \\
= & {\left[-P(y, t)-\frac{r_{1}^{\prime}}{r_{1}}\right] X^{2}+\left[-Q(y, t) \frac{r_{2}}{r_{1}}+\frac{r_{1}}{r_{2}}\right] X Y-\frac{r_{2}^{\prime}}{r_{2}} Y^{2} } \\
& \quad+[(P(\psi, t)-P(y, t)) \varphi+(Q(\psi, t)-Q(y, t)) \psi+F(y, t)-F(\psi, t)] \frac{X}{r_{1}} .
\end{aligned}
$$

In view of (6)-(8), the following estimates for $\pi(x, y, t)$ on $W$ are valid:

$$
\begin{aligned}
& \pi(x, y, t) \leq\left[-P(y, t)-\frac{r_{1}^{\prime}}{r_{1}}\right] X^{2}+\left|-Q(y, t) \frac{r_{2}}{r_{1}}+\frac{r_{1}}{r_{2}}\right||X||Y|+\left[-\frac{r_{2}^{\prime}}{r_{2}}\right] Y^{2} \\
& +\left(L_{1}|\varphi|+L_{2}|\psi|+L_{3}\right) \frac{r_{2}}{r_{1}}|X||Y| \\
& =\left[-P(y, t)-\frac{r_{1}^{\prime}}{r_{1}}\right] X^{2}+\left[\left(L_{1}|\varphi|+L_{2}|\psi|+L_{3}\right) \frac{r_{2}}{r_{1}}\right. \\
& \left.+\left|\frac{r_{1}}{r_{2}}-Q(y, t) \frac{r_{2}}{r_{1}}\right|\right]|X||Y|+\left[-\frac{r_{2}^{\prime}}{r_{2}}\right] Y^{2}, \\
& \pi(x, y, t) \geq\left[-P(y, t)-\frac{r_{1}^{\prime}}{r_{1}}\right] X^{2}-\left|-Q(y, t) \frac{r_{2}}{r_{1}}+\frac{r_{1}}{r_{2}}\right||X||Y|+\left[-\frac{r_{2}^{\prime}}{r_{2}}\right] Y^{2} \\
& -\left(L_{1}|\varphi|+L_{2}|\psi|+L_{3}\right) \frac{r_{2}}{r_{1}}|X||Y| \\
& =\left[-P(y, t)-\frac{r_{1}^{\prime}}{r_{1}}\right] X^{2}-\left[\left(L_{1}|\varphi|+L_{2}|\psi|+L_{3}\right) \frac{r_{2}}{r_{1}}\right. \\
& \left.+\left|\frac{r_{1}}{r_{2}}-Q(y, t) \frac{r_{2}}{r_{1}}\right|\right]|X||Y|+\left[-\frac{r_{2}^{\prime}}{r_{2}}\right] Y^{2} .
\end{aligned}
$$

The right-hand sides of the above inequalities are the quadratic symmetric forms

$$
a_{11} X^{2} \pm 2 a_{12}|X||Y|+a_{22} Y^{2}
$$

where corresponding coefficients $a_{11}, a_{12}, a_{22}$ are introduced.
(i) Conditions (14) and (15) imply

$$
a_{22}<0, \quad a_{11} a_{22}-a_{12}^{2}>0,
$$

which, according to Sylvester's criterion, means that $\pi(x, y, t)<0$ on $W$. Consequently, set $W$ is a set of points of strict entrance of integral curves of the system (5) with respect to the sets $\omega$ and $\Omega$. Hence, all solutions of the system (5) which satisfy the condition

$$
\begin{equation*}
\frac{\left(x_{0}-\varphi_{0}\right)^{2}}{r_{1}^{2}\left(t_{0}\right)}+\frac{\left(y_{0}-\psi_{0}\right)^{2}}{r_{2}^{2}\left(t_{0}\right)}<1, \tag{18}
\end{equation*}
$$

satisfy the inequality

$$
\begin{equation*}
\frac{(x(t)-\varphi(t))^{2}}{r_{1}^{2}(t)}+\frac{(y(t)-\psi(t))^{2}}{r_{2}^{2}(t)}<1, \quad \text { for } \quad t>t_{0} \tag{19}
\end{equation*}
$$

Since $x_{0}-\varphi_{0}=y_{0}^{\prime}-\psi_{0}^{\prime}$, then all solutions of the problem (1), (3) satisfy condition (16).
(ii) Conditions (14), (17) imply

$$
a_{22}>0, \quad a_{11} a_{22}-a_{12}^{2}>0,
$$

which, according to Sylvester's criterion, means that $\pi(x, y, t)>0$ on $W$. Consequently, $W$ is a set of points of strict exit of integral curves of the system (5) with respect to the sets $\omega$ and $\Omega$. Hence, according to retraction method, the problem (5), (18) has at least one solution satisfying condition (19). Consequently, the problem (1), (3) has at least one solution satisfying condition (16).

Now let us consider solutions of equation (1) which satisfy the condition

$$
\begin{equation*}
y_{0}^{2}+\left(y_{0}^{\prime}\right)^{2} \leq r^{2}\left(t_{0}\right) . \tag{20}
\end{equation*}
$$

Theorem 3. Let $r \in C^{1}(I), r(t)>0$. Then:
(i) If the conditions

$$
\begin{gather*}
F^{2}(y, t)<2 P(y, t)\left(2 r r^{\prime}-|1-Q(y, t)| r^{2}\right),  \tag{21}\\
P(y, t)>0 \tag{22}
\end{gather*}
$$

are satisfied, then all solutions $y(t)$ of the problem (1), (20) satisfy the condition

$$
\begin{equation*}
y^{2}(t)+y^{\prime 2}(t)<r^{2}(t), \quad \text { for } \quad t>t_{0} . \tag{23}
\end{equation*}
$$

(ii) If the conditions

$$
\begin{gather*}
F^{2}(y, t)<2 P(y, t)\left(2 r r^{\prime}+|1-Q(y, t)| r^{2}\right),  \tag{24}\\
P(y, t)<0, \tag{25}
\end{gather*}
$$

are satisfied, then at least one solution of the problem (1), (20) satisfies the condition (23).

Proof. We consider the system (5). Let $(\varphi(t), \psi(t), t), t \in I$, where $\varphi \in C^{1}(I)$, be an integral curve of the system (5), and consider the set

$$
\omega_{0}=\left\{(x, y, t) \in \Omega \mid x^{2}+y^{2} \leq r^{2}(t)\right\} .
$$

The boundary surface of $\omega_{0}$ is

$$
W_{0}=\left\{(x, y, t) \in \mathrm{Cl} \omega_{0} \mid H_{0}(x, y, t) \equiv x^{2}+y^{2}-r^{2}(t)=0\right\}
$$

Let $\nu(x, y, t)=\frac{1}{2} \nabla H_{0}(x, y, t)$ be a vector of the outer normal on the surface $W_{0}$. For the scalar product $\pi_{0}(x, y, t)=(\nu, T)$ on the surface $W_{0}$, we have:

$$
\begin{aligned}
\pi_{0}(x, y, t) & =[-P(y, t) x-Q(y, t) y+F(y, t)] x+x y-r r^{\prime} \\
& =-P(y, t) x^{2}+[1-Q(y, t)] x y+F(y, t) x-r r^{\prime}
\end{aligned}
$$

According to the conditions (21), (22), and (24), (25), and by using the inequality $a b \leq \frac{1}{2}\left(a^{2}+b^{2}\right)$, for $a, b \in \mathbb{R}$, the following estimates for $\pi_{0}(x, y, t)$ on $W_{0}$ are valid in the cases ( $i$ ) and (ii), respectively:

$$
\begin{aligned}
\pi_{0}(x, y, t) & \leq-P(y, t) x^{2}+F(y, t) x+\frac{1}{2}|1-Q(y, t)|\left(x^{2}+y^{2}\right)-r r^{\prime} \\
& =-P(y, t) x^{2}+F(y, t) x+\frac{1}{2}|1-Q(y, t)| r^{2}-r r^{\prime}<0 \\
\pi_{0}(x, y, t) & \geq-P(y, t) x^{2}+F(y, t) x-\frac{1}{2}|1-Q(y, t)|\left(x^{2}+y^{2}\right)-r r^{\prime} \\
& =-P(y, t) x^{2}+F(y, t) x-\frac{1}{2}|1-Q(y, t)| r^{2}-r r^{\prime}>0
\end{aligned}
$$

According to Lemma 1 and Lemma 2, the above estimates for $\pi_{0}$ imply the statement of the theorem.

Example 1. For the problem

$$
\begin{equation*}
y^{\prime \prime}+f(y, t) y^{\prime}-f(y, t) \sin 2 t-2 \cos 2 t=0 \tag{26}
\end{equation*}
$$

with

$$
\begin{equation*}
\left|y_{0}-\sin ^{2} t_{0}\right| \leq \beta \exp \left(-s t_{0}\right), \quad\left|y_{0}^{\prime}-\sin 2 t_{0}\right| \leq \alpha \exp \left(-s t_{0}\right) \tag{27}
\end{equation*}
$$

where $\alpha, \beta, s \in \mathbb{R}, \alpha>0, \beta>0, s \geq 0, \alpha<\beta s$, we have:
If function $f(y, t)$ satisfies the Lipschitz's condition with respect to the variable $y$, with Lipschitz's constant L, and the condition

$$
f(y, t)>s+\frac{2 \beta}{\alpha} L \quad \text { on } \quad \mathbb{R} \times I
$$

for all $y$, then the problem (26), (27) has one-parameter class of solutions satisfying the condition

$$
\left|y(t)-\sin ^{2} t\right| \leq \beta \exp (-s t), \quad\left|y^{\prime}(t)-\sin 2 t\right| \leq \alpha \exp (-s t), \quad \text { for } \quad t>t_{0}
$$

This result follows from Theorem 1, with $r_{1}(t)=\alpha \exp (-s t), r_{2}(t)=\beta \exp (-s t)$.
Example 2. For the Van der Pol equation

$$
\begin{equation*}
y^{\prime \prime}-\mu(1-\Phi(y)) y^{\prime}+y=0, \quad \mu>0 \tag{28}
\end{equation*}
$$

and the condition

$$
\begin{equation*}
y^{2}\left(t_{0}\right)+y^{\prime 2}\left(t_{0}\right) \leq \ln ^{2} t_{0}, \tag{29}
\end{equation*}
$$

we can prove the following:
If function $\Phi(y)>1$, then all solutions of the problem (28), (29) satisfy the condition

$$
y^{2}(t)+y^{\prime 2}(t) \leq \ln ^{2} t, \quad \text { for } \quad t \in\left(t_{0}, \infty\right), \quad t_{0}>1
$$

This result follows from Theorem 3, with $r(t)=\ln t$.

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